

Dynamic Programming

Formulating dynamic programs – two ways

- A **dynamic program** models situations where decisions are made in a sequential process in order to optimize some objective
- **Stages** $t = 1, 2, \dots, T$
 - stage $T \leftrightarrow$ end of decision process
- **States** $n = 0, 1, \dots, N \leftarrow$ possible conditions of the system at each stage
- Two representations: **shortest/longest path** and **recursive**

Shortest/longest path	Recursive
node t_n	\leftrightarrow state n at stage t
edge $(t_n, (t+1)_m)$	\leftrightarrow allowable decision x_t in state n at stage t that results in being in state m at stage $t+1$
length of edge $(t_n, (t+1)_m)$	\leftrightarrow cost/reward of decision x_t in state n at stage t that results in being in state m at stage $t+1$
length of shortest/longest path from node t_n to end node	\leftrightarrow cost/reward-to-go function $f_t(n)$
length of edges (T_n, end)	\leftrightarrow boundary conditions $f_T(n)$
shortest or longest path	\leftrightarrow recursion is min or max: $f_t(n) = \min_{x_t \text{ allowable}} \text{ or } \max \left\{ \left(\begin{array}{c} \text{cost/reward of} \\ \text{decision } x_t \end{array} \right) + f_{t+1} \left(\begin{array}{c} \text{new state} \\ \text{resulting} \\ \text{from } x_t \end{array} \right) \right\}$
source node 1_n	\leftrightarrow desired cost-to-go function value $f_1(n)$

- Note that the length of edge (T_n, end) is often 0, but not always!

Example 1. Simplexville Oil needs to build capacity to refine 1,000 barrels of oil and 2,000 barrels of gasoline per day. Simplexville can build a refinery at 2 locations. The cost of building a refinery is as follows:

Oil capacity per day	Gas capacity per day	Building cost (\$ millions)
0	0	0 ← length of red edges
1000	0	5 ← length of blue edges
0	1000	7 ← length of orange edges
1000	1000	14 ← length of green edges

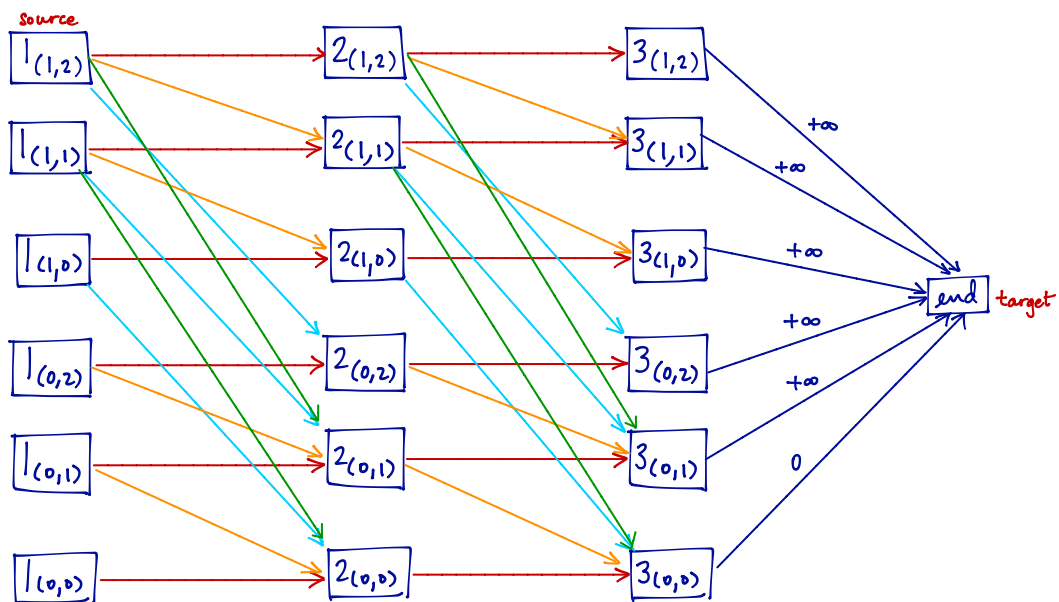
The problem is to determine how much capacity should be built at each location in order to minimize the total building cost. To make things a little simpler, assume that the capacity requirements must be met exactly.

- Formulate this problem as a dynamic program by giving its shortest path representation.
- Formulate this problem as a dynamic program by giving its recursive representation. Solve the dynamic program.

a. Stages: $t = 1, 2 \leftrightarrow$ building at location t $t = 3 \leftrightarrow$ end of process

States: $(n_1, n_2) \leftrightarrow n_1$ oil capacity and n_2 gas capacity still needed to be built
(in 1000s) for $n_1 \in \{0, 1\}$ and $n_2 \in \{0, 1, 2\}$

Find the shortest path:



b. Stages: $t=1, 2 \leftrightarrow$ building at location t $t=3 \leftrightarrow$ end of process

States: $(n_1, n_2) \leftrightarrow$ n_1 , oil capacity and n_2 gas capacity still needed to be built
(in 1000s) for $n_1 \in \{0, 1\}$ and $n_2 \in \{0, 1, 2\}$

Allowable decisions x_t at stage t and state (n_1, n_2) :

$t=1, 2$: $x_t = (x_{t1}, x_{t2}) \leftrightarrow$ build x_{t1} oil capacity and x_{t2} gas capacity at location t

x_t must satisfy: $(x_{t1}, x_{t2}) \in \{(0,0), (1,0), (0,1), (1,1)\}$

$$x_{t1} \leq n_1$$

$$x_{t2} \leq n_2$$

Cost of x_t at stage t and state (n_1, n_2) : $C(x_t) = \begin{cases} 0 & \text{if } x_t = (0,0) \\ 5 & \text{if } x_t = (1,0) \\ 7 & \text{if } x_t = (0,1) \\ 14 & \text{if } x_t = (1,1) \end{cases}$

Cost-to-go function: $f_t(n_1, n_2) =$ minimum cost to build n_1 oil capacity and n_2 gas capacity
with locations $t, t+1, \dots$ for $t=1, 2, 3$; $n_1 = 0, 1$; $n_2 = 0, 1, 2$

Boundary conditions: $f_3(n_1, n_2) = \begin{cases} 0 & \text{if } (n_1, n_2) = (0,0) \\ +\infty & \text{o/w} \end{cases}$ for $n_1 = 0, 1$; $n_2 = 0, 1, 2$

Recursion: $f_t(n_1, n_2) = \min_{\substack{(x_{t1}, x_{t2}) \\ \text{allowable}}} \{ C(x_{t1}, x_{t2}) + f_{t+1}(n_1 - x_{t1}, n_2 - x_{t2}) \}$ for $t=1, 2$; $n_1 = 0, 1$;
 $n_2 = 0, 1, 2$

Desired cost-to-go value: $f_1(1, 2)$

Solving backwards:

$$\text{Stage 3: } f_3(n_1, n_2) = \begin{cases} 0 & \text{if } (n_1, n_2) = (0, 0) \\ +\infty & \text{o/w} \end{cases} \quad \text{for } n_1 = 0, 1; \quad n_2 = 0, 1, 2$$

(boundary conditions)

$$\text{Stage 2: } f_2(1, 2) = \min\{0 + f_3(1, 2), 5 + f_3(0, 2), 7 + f_3(1, 1), 14 + f_3(0, 1)\} = +\infty$$

$$f_2(1, 1) = \min\{0 + f_3(1, 1), 5 + f_3(0, 1), 7 + f_3(1, 0), 14 + f_3(0, 0)\} = 14$$

$$f_2(1, 0) = \min\{0 + f_3(1, 0), 5 + f_3(0, 0)\} = 5$$

$$f_2(0, 2) = \min\{0 + f_3(0, 2), 7 + f_3(0, 1)\} = +\infty$$

$$f_2(0, 1) = \min\{0 + f_3(0, 1), \underline{7 + f_3(0, 0)}\} = 7 \quad x_2 = (0, 1)$$

$$f_2(0, 0) = \min\{0 + f_3(0, 0)\} = 0$$

$$\text{Stage 1: } f_1(1, 2) = \min\{0 + f_2(1, 2), 5 + f_2(0, 2), 7 + f_2(1, 1), \underline{14 + f_2(0, 1)}\} = 21 \quad x_1 = (1, 1)$$

(desired cost-to-go)

Note that $x_1 = (0, 1)$ and $x_2 = (1, 1)$ is also an optimal solution.